

Soient  $f$  et  $g$  définie sur  $\mathbb{R}^2$  par  $f(x,y) = x^2e^{xy}$  et  $g(x,y,z) = (5x^2 - 3xz ; (z + y)^2 ; x - y + z)$

Calculer :

a) [1pt]  $\nabla(f)$ .

d) [1pt]  $\text{rot}(g)$ .

b) [1pt]  $\Delta(f)$ .

e) [1pt]  $H_f(x,y)$ .

c) [1pt]  $\text{div}(g)$ .

Corrigé

$$a) \nabla(f) = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix} = \begin{bmatrix} 2xe^{xy} + x^2ye^{xy} \\ x^2ye^{xy} \end{bmatrix} = \begin{bmatrix} (2x + x^2y)e^{xy} \\ x^2ye^{xy} \end{bmatrix}$$

$$b) \Delta(f) = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = (2 + 2xy)e^{xy} + y(2x + x^2y)e^{xy} + x^4e^{xy} = (2 + 4xy + x^2y^2 + x^4)e^{xy}$$

$$c) \text{div}(g) = \frac{\partial g_1}{\partial x} + \frac{\partial g_2}{\partial y} + \frac{\partial g_3}{\partial z} = 10x - 3z + 2(z + y) + 1 = 10x - z + 2y + 1$$

$$d) \text{rot}(g) = \begin{bmatrix} \frac{\partial f_3}{\partial y} - \frac{\partial f_2}{\partial z} \\ \frac{\partial f_1}{\partial z} - \frac{\partial f_3}{\partial x} \\ \frac{\partial f_2}{\partial x} - \frac{\partial f_1}{\partial y} \end{bmatrix} = \begin{bmatrix} -1 - 2(y + z) \\ -3x - 1 \\ 0 - 0 \end{bmatrix}$$

$$e) H_f(x,y) = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial y \partial y} \\ \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix} = \begin{bmatrix} (2 + 4xy + x^2y^2)e^{xy} & (3x^2 + x^3y)e^{xy} \\ (3x^2 + x^3y)e^{xy} & x^4e^{xy} \end{bmatrix}$$